

# **DAVICOM Semiconductor, Inc.**

# DM9161A

# 10/100 Mbps Fast Ethernet Physical Layer Single Chip Transceiver

# **DATA SHEET**

Final

Version: DM9161A-DS-F01





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#### 1. General Description

The DM9161A is a physical layer, single-chip, and low power transceiver for 100BASE-TX and 10BASE-T operations. On the media side, it provides a direct interface either to Unshielded Twisted Pair Category 5 Cable (UTP5) for 100BASE-TX Fast Ethernet, or UTP5/UTP3 Cable for 10BASE-T Ethernet. Through the Media Independent Interface (MII), the DM9161A connects to the Medium Access Control (MAC) layer, ensuring a high inter operability from different vendors.

TheDM9161A uses a low power and high performance advanced CMOS process. It contains the entire physical layer functions of 100BASE-TX as defined by IEEE802.3u, including the Physical Coding Sublayer (PCS), Physical Medium Attachment (PMA), Twisted Pair Physical Medium Dependent Sublayer (TP-PMD), 10BASE-TX Encoder/Decoder (ENC/DEC), and Twisted Pair Media Access Unit (TPMAU). The DM9161A provides a strong support for the auto-negotiation function, utilizing automatic media speed and protocol selection. Furthermore, due to the built-in wave shaping filter, the DM9161A needs no external filter to transport signals to the media in 100BASE-TX or 10BASE-T Ethernet operation.

#### 2. Features

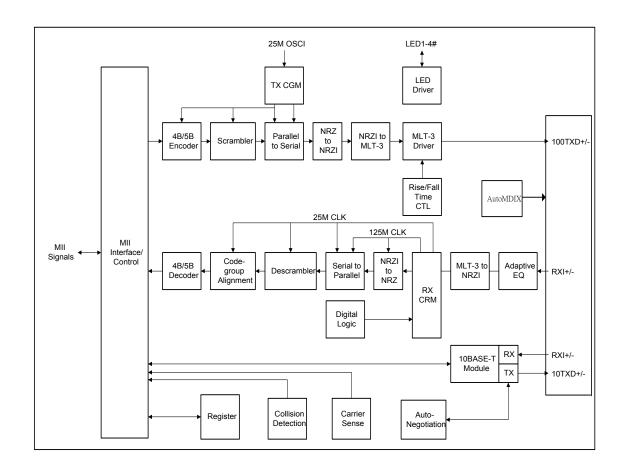
- Fully comply with IEEE 802.3 / IEEE 802.3u 10Base-T/ 100Base-TX, ANSI X3T12 TP-PMD 1995 standard
- Support MDI/MDI-X auto crossover function (Auto-MDI)
- Support Auto-Negotiation function, compliant with IEEE 802.3u
- Fully integrated Physical layer transceiver On-chip filtering with direct interface to magnetic transformer
- Selectable repeater or node mode
- Selectable MII or RMII (Reduced MII) mode for 100Base-TX and 10Base-TX. Selectable MII or GPSI (7-Wired) mode for 10Base-T
- Selectable full-duplex or half-duplex operation
- MII management interface with maskable interrupt output capability

- Provide Loopback mode for easy system diagnostics
- LED status outputs indicate Link/ Activity, Speed10/100 and Full-duplex/Collision. Support Dual-LED optional control
- Single low power Supply of 3.3V with an advanced CMOS technology
- Very Low Power consumption modes:
  - Power Reduced mode (cable detection)
  - Power Down mode
  - Selectable TX drivers for 1:1 or 1.25:1 transformers for additional power reduction. 1: 1 transformers only when HP Auto-MDIX Enable.
- Compatible with 3.3V and 5.0V tolerant I/Os
- 48-pin LQFP

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# 3. Block Diagram

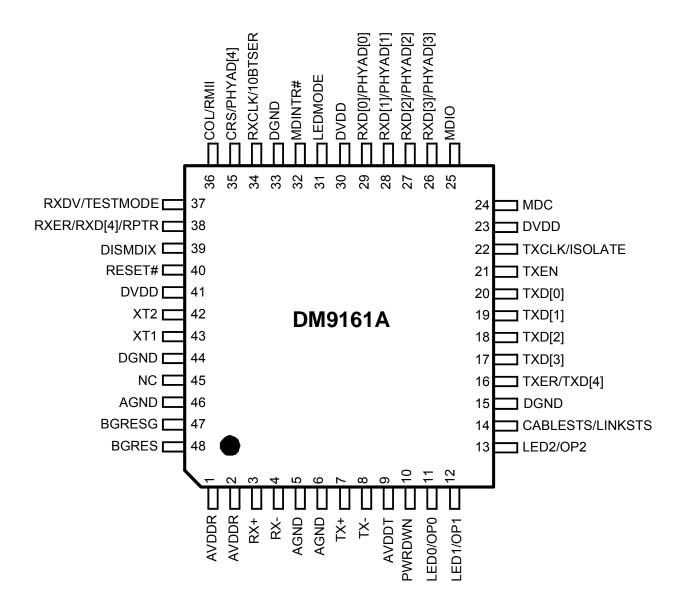


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# 4. Pin Configuration:



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# 5. Pin Description

I: Input, O: Output, LI: Latch input when power-up/reset, Z: Tri-State output, U: Pulled high D: Pulled low

5.1 Normal MII Interface, 21 pins

Pin No.	Pin Name	I/O	Description			
16	TXER/TXD [4]	I	Transmit Error/The Fifth TXD Data Bit In 100Mbps mode, when the signal indicates active high and TXEN is active, the HALT symbol substitutes the actual data nibble. In 10Mbps, the input is ignored In bypass mode (bypass BP4B5B), TXER becomes the TXD [4] pin, the fifth TXD data bit of the 5B symbol			
20,19,18,17	TXD [0:3]	I	Transmit Data 4-bit nibble data inputs (synchronous to the TXCLK) when in 10/100Mbps nibble mode. In 10Mbps GPSI (7-Wired) mode, the TXD [0] pin is used as the serial data input pin, and TXD [1:3] are ignored.			
21	TXEN	I	Transmit Enable Active high indicates the presence of valid nibble data on the TXD [0:3] for both 100Mbps and 10Mbps nibble modes. In 10Mbps GPSI (7-Wired) mode, active high indicates the presence of valid 10Mbps data on TXD [0].			
22	TXCLK/ ISOLATE	O, Z, LI (D)	Transmit Clock The transmitting clock provides the timing reference for the transfer of the TXEN, TXD, and TXER. TXCLK is provided by the PHY 25MHz in 100Mbps nibble mode, 2.5MHz in 10Mbps nibble mode, 10MHz in 10Mbps GPSI (7-Wired) mode ISOLATE Setting: (When power up reset, latch input) 0: Reg 0.10 will be initialized to "0". (Ref.to 8.1 Basic Control Register) 1: Reg 0.10 will be initialized to "1".			
24	MDC	I	Management Data Clock Synchronous clock for the MDIO management data. This clock is provided by management entity, and it is up to 12.5MHz			
25	MDIO	I/O	Management Data I/O Bi-directional management data which may be provided by the station management entity or the PHY			
29,28,27,26	RXD[0:3] /PHYAD[0:3]	O, Z, LI (D)	Receive Data Output 4-bit nibble data outputs (synchronous to RXCLK) when in 10/100Mbps MII mode In 10Mbps GPSI (7-Wired) mode, the RXD [0] pin is used as the serial data output pin, and the RXD [1:3] are ignored PHY address [0:3] (power up reset latch input) PHY address sensing input pins			
32	MDINTR	IO, LI (D)	Status Interrupt Output: Whenever there is a status change (link, speed, duplex depend on interrupt register [21]) The interrupt output assert low when pull up. Asserted high when pull down.			

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34	RXCLK /10BTSER	O, Z, LI (U)	RXCLK reference from a nominal clock 25MHz in 100Mbps MII mode, 2.5MHz in 10Mbps MII mode, 10MHz in 10Mbps GPSI (7-Wired) mode 10BTSER only support for 10M mode; (power up reset latch input) 0 = GPSI (7-Wired) mode in 10M mode 1 = MII mode in 10M mode
35	CRS /PHYAD[4]	O, Z, LI (D)	activities in half-duplex mode of 10BASE-T or 100BASE-TX. In repeater mode or full-duplex mode, this signal is asserted high to indicate the presence of carrier due to receive activity only This pin is also used as PHYAD [4] (power up reset latch input) PHY address sensing input pin
36	COL /RMII	O, Z, LI (D)	Collision Detection Asserted high to indicate the detection of the collision conditions in half-duplex mode of 10Mbps and 100Mbps. In full-duplex mode, this signal is always logical 0 Reduced MII enable: This pin is also used to select Normal MII or Reduced MII. (power up reset latch input) 0= Normal MII (default) 1= Reduced MII This pin is always pulled low except used as reduced MII
37	RXDV /TESTMODE	O, Z, LI (D)	Receive Data Valid Asserted high to indicate that the valid data is presented on the RXD [0:3] Test mode control pin (power up reset latch input)
38	RXER/RXD[4] /RPTR	O, Z, LI (D)	Asserted high to indicate that an invalid symbol has been detected In decoder bypass mode (bypass BP4B5B), RXER becomes RXD [4], the
31	LEDMODE	1	LED MODE Select Reference LED function description 0: support Dual-LED 1: Normal LED
40	RESET#	Ι	Reset Active low input that initializes the DM9161A.

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## 5.2 Media Interface, 4 pins

Pin No.	Pin Name	I/O	Description			
3,4	RX+	-	ifferential Receive Pair			
	RX-		Differential data is received from the media			
7,8	TX+	0	Differential Transmit Pair/PECL Transmit Pair			
	TX-		Differential data is transmitted to the media in TP mode			

## 5.3 LED Interface, 3 pins

Pin No.	Pin Name	I/O	Description		
11	LED0	Ο,	LED Driver output 0		
	/OP0	LI	OP0: (power up reset latch input)		
		(U)	This pin is used to control the forced or advertised operating mode of the		
			DM9161A according to the Table A. The value is latched into the		
			DM9161A registers at power-up/reset		
12	LED1	Ο,			
	/OP1	LI	LED Driver output 1		
		(U)	P1: (power up reset latch input)		
			This pin is used to control the forced or advertised operating mode of the		
			DM9161A according to the Table A. The value is latched into the		
			DM9161A registers at power-up/reset		
13	LED2	Ο,	LED Driver output 2		
	/OP2	LI	OP2: (power up reset latch input)		
		(U)	This pin is used to control the forced or advertised operating mode of the		
			DM9161A according to the Table A. The value is latched into the		
			DM9161A registers at power-up/reset		

# 5.4 Mode, 3 pins

Pin No.	Pin Name	I/O	Description
10	PWRDWN	I	Power Down Control Asserted high to force the DM9161A into power down mode. When in power down mode, most of the DM9161A circuit block's power is turned off, only the MII management interface (MDC, MDIO) logic is available (the PHY should respond to management transactions and should not generate spurious signals on the MII)). To leave power down mode, the DM9161A needs the hardware or software reset with the PWRDWN pin low
14	CABLESTS /LINKSTS	O, LI (D)	Cable Status or Link Status This pin is used to indicate the status of the cable connection when power up reset latch low (Default) 0 = Without cable connection 1 = With cable connection This pin is used to indicate the status of the Link connection when power up reset latch high 0 = With link 1 = Without link
39	DISMDIX	I (D)	HP Auto-MDIX Control 1: Disable auto mode 0: Enable HP Auto-MDIX mode

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## 5.5 Bias and Clock, 4 pins

Pin No.	Pin Name	I/O	Description			
47	BGRESG	Р	andgap Ground			
48	BGRES	0	Bandgap Voltage Reference Resistor 6.8K ohm +/- 1%			
42	XT2	I/O	Crystal Output; REF_CLK input for RMII mode			
43	XT1	I	Crystal Input			

## 5.6 Power, 12 pins

Pin No.	Pin Name	I/O	Description
1,2	AVDDR	Р	Analog Receive Power output
9	AVDDT	Р	Analog Transmit Power output
5	AGND	Р	Analog Receive Ground
6	AGND	Р	Analog Transmit Ground
46	AGND	Р	Analog Substrate Ground
23,30,41	DVDD	Р	Digital Power
15,33,44	DGND	Р	Digital Ground

# 5.7 Table A (Media Type Selection)

OP2	OP1	OP0	Function		
0	0	0	Dual Speed 100/10 HDX		
0	0	1	Reserved		
0	1	0	Reserved		
0	1	1	Manually Select 10TX HDX		
1	0	0	Manually Select 10TX FDX		
1	0	1	Manually Select 100TX HDX		
1	1	0	Manually Select 100TX FDX		
1	1	1	Auto-negotiation Enables All Capabilities		

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# 5.8 Pin Maps of Normal MII, Reduced MII, and 10Base-T GPSI (7-Wired) Mode

Normal MII Mode	Reduced MII Mode	10Base-T GPSI (7-Wired) Mode
TXD [0:1]	TXD [0:1]	TXD [0] ; TXD [1] = NC
TXD [2:3]	NC	NC
TXEN	TXEN	TXEN
TXER/TXD [4]	NC	NC
TXCLK	NC	TXCLK
RXD [0:1]	RXD [0:1]	RXD [0] ; RXD [1] = NC
RXD[2:3]	NC	NC
RXER/RXD[4]/RPTR/NODE	RPTR/NODE	RPTR/NODE
RXDV	CRS DV	NC
RXCLK	NC	RXCLK
COL	NC	COL
CRS	NC	CRS
(PHYADR [2:4])		
(BP4B5B)		
MDC	MDC	MDC
MDIO	MDIO	MDIO
RESET#	RESET#	RESET#
XT1 (25 MHz)	XT2 (REF_CLK 50MHz)	XT1 (25 MHz)

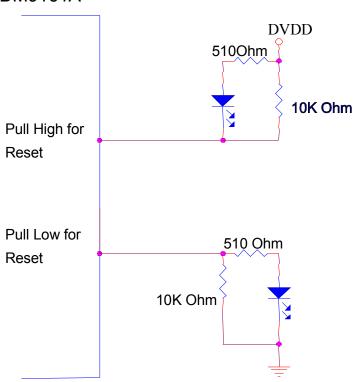
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# **6.LED Configuration**

LEDs flash once per 500ms after power-on reset or software reset by writing PHY register. All LED pins are dual function pins, which can be configured as either active high or low by pulling them low or high accordingly. If the pin is pulled high, the LED is active low after reset. Likewise, if the pin is pulled low, the LED is active high.

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# **6.1 LED Function Description**

#### Normal LED mode

			LED_MODE = 1			
Name	Pin	Lo	Hi	Lo	Hi	
LED0	11	FDX	HDX	FDX	HDX	
LED1	12	SPEED: 100M	SPEED: 10M	SPEED: 100M	SPEED: 10M	
CABLESTS /	LINKSTS	Pull [	Down	Pull Up		
Name	Pin	Lo	Hi	Lo	Hi	
LEDO	40	LED2 42	Link	Link Fail	N	/A
LED2	13	Flashing (F	liLo) Active	Flashing (H	liLo) Active	
CABLESTS / LINKSTS	14	Without Cable connection	With Cable connection	With Link	Without Link	

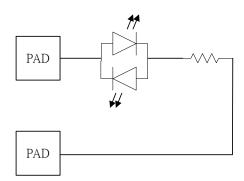
<sup>\*</sup> Pin 31 = LEDMODE

#### For Dual-LED.

TOT DUAI-LLD.										
			LED_MOD	E=0						
			LINK Mode							
Name	Pin	Link Fail	SPEED	D: 100M		S	PEED: 10M			
		LINK Fall	Link OK	Ac	tive	Link OK	Active			
LED0	11	Lo	Lo	Flashin	g (LoHi)	HI	Flashing (HiLo)			
LED1	12	Lo	Hi Lo			Lo				
CABLESTS /	LINKSTS	Pull	Down		Pull Up					
Name	Pin	Lo	Hi			Lo	Hi			
							HDX			
LED2	13	FDX	HDX			FDX	Flashing (LoHi)			
							Collision			
CABLESTS / LINKSTS	14	Without Cable connection	With Cable co	onnection	W	ith Link	Without Link			

<sup>\*</sup> Pin 31 = LEDMODE

<sup>6.1.1</sup> Dual-LED application circuit.



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#### 7. Functional Description

The DM9161A Fast Ethernet single chip transceiver, providing the functionality as specified in IEEE 802.3u, integrates a complete 100Base-TX module and a complete 10Base-T module. The DM9161A provides a Media Independent Interface (MII) as defined in the IEEE 802.3u standard (Clause 22).

The DM9161A performs all PCS (Physical Coding Sublayer), PMA (Physical Media Access), TP-PMD (Twisted Pair Physical Medium Dependent) sublayer, 10Base-T Encoder/Decoder, and Twisted Pair Media Access Unit (TPMAU) functions. Figure 7-1 shows the major functional blocks implemented in the DM9161A.

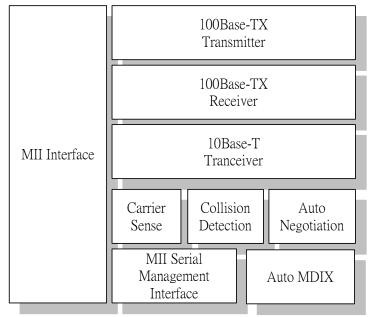


Figure 7-1

#### 7.1 MII Interface

The DM 9161A provides a Media Independent Interface (MII) as defined in the IEEE 802.3u standard (Clause 22).

The purpose of the MII interface is to provide a simple, easy to implement connection between the MAC Reconciliation layer and the PHY. The MII is designed to make the differences between various media transparent to the MAC sublayer.

The MII consists of a nibble wide receive data bus, a nibble wide transmit data bus, and control signals to facilitate data transfers between the PHY and the Reconciliation layer.

 TXD (transmit data) is a nibble (4 bits) of data that are driven by the reconciliation sublayer synchronously with respect to TXCLK. For each TXCLK period, which TXEN is asserted, TXD (3:0) are accepted for transmission by the PHY.

- TXCLK (transmit clock) output to the MAC reconciliation sublayer is a continuous clock that provides the timing reference for the transfer of the TXEN, TXD, and TXER signals.
- TXEN (transmit enable) input from the MAC reconciliation sublayer indicates that nibbles are being presented on the MII for transmission on the physical medium.

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#### MII Interface (continued)

- (transmit coding error) transitions synchronously with respect to TXCLK. If TXER is asserted for one or more clock periods, and TXEN is asserted, the PHY will emit one or more symbols that are not part of the valid data delimiter set somewhere in the frame being transmitted.
- RXD (receive data) is a nibble (4 bits) of data that are sampled by the reconciliation sublayer synchronously with respect to RXCLK. For each RXCLK period which RXDV is asserted, RXD (3:0) are transferred from the PHY to the MAC reconciliation sublayer.
- RXCLK (receive clock) output to the MAC reconciliation sublaver is a continuous clock that provides the timing reference for the transfer of the RXDV, RXD, and RXER signals.
- RXDV (receive data valid) input from the PHY indicates that the PHY is presenting recovered and decoded nibbles to the MAC reconciliation sublayer. To interpret a receive frame correctly by the reconciliation sublayer, RXDV must encompass the frame, starting no later than the Start-of-Frame delimiter and excluding any End-Stream delimiter.
- RXER (receive error) transitions are synchronously with respect to RXCLK. RXER will be asserted for 1 or more clock periods to indicate to the reconciliation sublayer that an error was detected somewhere in the frame being transmitted from the PHY to the reconciliation sublayer.
- CRS (carrier sense) is asserted by the PHY when either the transmit or receive medium is non-idle, and de-asserted by the PHY when the transmit and receive medium are idle. Figure 7-2 depicts the behavior of CRS during 10Base-T and 100Base-TX transmission.

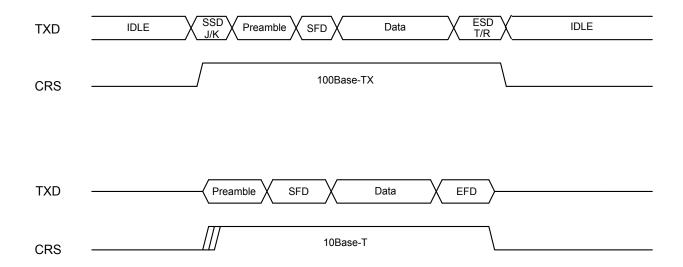


Figure 7-2



#### 7.2 100Base-TX Operation

The 100Base-TX transmitter receives 4-bit nibble data clocked in at 25MHz at the MII, and outputs a scrambled 5-bit encoded MLT-3 signal to the media at 100Mbps. The on-chip clock circuit converts the 25MHz clock into a 125MHz clock for internal use.

The IEEE 802.3u specification defines the Media Independent Interface. The interface specification defines a dedicated receive data bus and a dedicated transmit data bus.

These two busses include various controls and signal indications that facilitate data transfers between the DM9161A and the Reconciliation layer.

## 7.2.1 100Base-TX Transmit

The 100Base-TX transmitter consists of the functional blocks shown in figure 7-3. The 100Base-TX transmit section converts 4-bit synchronous data provided by the MII to a scrambled MLT-3 125, a million symbols per second serial data stream.

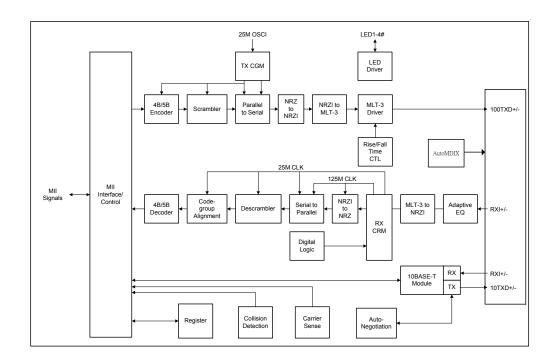


Figure 7-3

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The block diagram in figure 7-3 provides an overview of the functional blocks contained in the transmit section.

The transmitter section contains the following functional blocks:

- 4B5B Encoder
- Scrambler
- Parallel to Serial Converter
- NRZ to NRZI Encoder
- NRZI to MLT-3
- MLT-3 Driver

#### 7.2.1.1 4B5B Encoder

The 4B5B encoder converts 4-bit (4B) nibble data generated by the MAC Reconciliation Layer into a 5-bit (5B) code group for transmission, see reference Table 7-1. This conversion is required for control and packet data to be combined in code groups. The 4B5B encoder substitutes the first 8 bits of the MAC preamble with a J/K code group pair (11000 10001) upon transmit. The 4B5B encoder continues to replace subsequent 4B preamble and data nibbles with corresponding 5B code-groups. At the end of the transmit packet, upon the deassertion of the Transmit Enable signal from the MAC Reconciliation layer, the 4B5B encoder injects the T/R code group pair (01101 00111) indicating end of frame. After the T/R code group pair, the 4B5B encoder continuously injects IDLEs into the transmit data stream until Transmit Enable is asserted and the next transmit packet is detected.

The DM9161A includes a Bypass 4B5B conversion option within the 100Base-TX Transmitter for support of applications like 100 Mbps repeaters, which do not require 4B5B conversion.

#### 7.2.1.2 Scrambler

The scrambler is required to control the radiated emissions (EMI) by spreading the transmit energy across the frequency spectrum at the media connector and on the twisted pair cable in 100Base-TX operation.

By scrambling the data, the total energy presented to the cable is randomly distributed over a wide frequency range. Without the scrambler, energy levels on the cable could peak beyond FCC limitations at frequencies related to repeated 5B sequences like continuous transmission of IDLE symbols. The scrambler output is combined with the NRZ 5B data from the code group encoder via an XOR logic function. The result is a scrambled data stream with sufficient randomization to decrease radiated emissions at critical frequencies.

#### 7.2.1.3 Parallel to Serial Converter

The Parallel to Serial Converter receives parallel 5B scrambled data from the scrambler and serializes it (converts it from a parallel to a serial data stream). The serialized data stream is then presented to the NRZ to NRZI encoder block

#### 7.2.1.4 NRZ to NRZI Encoder

Since the transmit data stream has been scrambled and serialized, the data must be NRZI encoded for compatibility with the TP-PMD standard for 100Base-TX transmission over Category-5 unshielded twisted pair cable.

#### 7.2.1.5 MLT-3 Converter

The MLT-3 conversion is accomplished by converting the data stream output from the NRZI encoder into two binary data streams with alternately phased logic one events.

#### 7.2.1.6 MLT-3 Driver

The two binary data streams, created at the MLT-3 converter, are fed to the twisted pair output driver, which converts these streams to current sources and alternately drives either side of the transmit transformer's primary winding, resulting in a minimal current MLT-3 signal. Refer to figure 7-4 for the block diagram of the MLT-3 converter.



## 7.2.1.7 4B5B Code Group

Symbol	Meaning	4B code	5B Code
		3210	43210
0	Data 0	0000	11110
1	Data 1	0001	01001
2	Data 2	0010	10100
3	Data 3	0011	10101
4	Data 4	0100	01010
5	Data 5	0101	01011
6	Data 6	0110	01110
7	Data 7	0111	01111
8	Data 8	1000	10010
9	Data 9	1001	10011
Α	Data A	1010	10110
В	Data B	1011	10111
С	Data C	1100	11010
D	Data D	1101	11011
Е	Data E	1110	11100
F	Data F	1111	11101
	Idle	undefined	11111
J	SFD (1)	0101	11000
K	SFD (2)	0101	10001
Т	ESD (1)	undefined	01101
R	ESD (2)	undefined	00111
Н	Error	undefined	00100
V	Invalid	undefined	00000
V	Invalid	undefined	00001
V	Invalid	undefined	00010
V	Invalid	undefined	00011
V	Invalid	undefined	00101
V	Invalid	undefined	00110
V	Invalid	undefined	01000
V	Invalid	undefined	01100
V	Invalid	undefined	10000
V	Invalid	undefined	11001

Table 7-1

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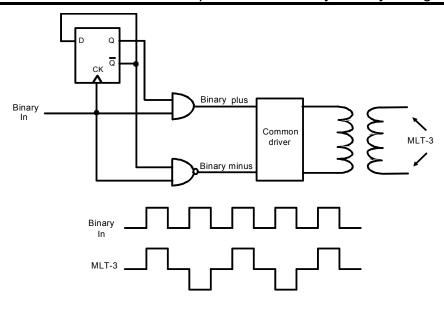


Figure 7-4

#### 7.2.2 100Base-TX Receiver

The 100Base-TX receiver contains several function blocks that convert the scrambled 125Mb/s serial data to synchronous 4-bit nibble data, which is then provided to the MII.

The receive section contains the following functional blocks:

- Signal Detect
- Adaptive Equalizer
- MLT-3 to NRZI Decoder
- Clock Recovery Module
- NRZI to NRZ Decoder
- Serial to Parallel
- Descrambler
- Code Group Alignment
- 4B5B Decoder

#### 7.2.2.1 Signal Detect

The signal detect function meets the specifications mandated by the ANSI XT12 TP-PMD 100Base-TX Standards for both voltage thresholds and timing parameters.

#### 7.2.2.2 Adaptive Equalizer

When transmitting data at high speeds over copper twisted pair cable, attenuation based on frequency becomes a concern. In high speed twisted pair signaling, the frequency content of the transmitted signal can vary greatly during normal operation based on the randomness of the scrambled data stream. This variation in signal attenuation caused by frequency variations must be compensated for to ensure the integrity of the received data. In order to ensure quality transmission when employing MLT-3 encoding, the compensation must be able to adapt to various cable lengths and cable types depending on the installed environment. The selection of long cable lengths for a given implementation requires significant compensation, which will be over-kill in a situation that includes shorter, less attenuating cable lengths. Conversely, the selection of short or intermediate cable lengths requiring less compensation will cause serious under-compensation for longer length cables. Therefore, the compensation or equalization must be adaptive to ensure proper conditioning of the received signal independent of the cable length.

#### 7.2.2.3 MLT-3 to NRZI Decoder

The DM9161A decodes the MLT-3 information from the Digital Adaptive Equalizer into NRZI data. The relation between NRZI and MLT-3 data is shown in figure 7-4.

The Clock Recovery Module accepts NRZI data from the

#### 7.2.2.4 Clock Recovery Module





MLT-3 to NRZI decoder. The Clock Recovery Module locks onto the data stream and extracts the 125MHz reference clock. The extracted and synchronized clock and data are presented to the NRZI to NRZ Decoder.

#### **7.2.2.5 NRZI to NRZ**

The transmit data stream is required to be NRZI encoded in for compatibility with the TP-PMD standard for 100Base-TX transmission over Category-5 unshielded twisted pair cable. This conversion process must be reversed on the receive end. The NRZI to NRZ decoder, receives the NRZI data stream from the Clock Recovery Module and converts it to a NRZ data stream to be presented to the Serial to Parallel conversion block.

#### 7.2.2.6 Serial to Parallel

The Serial to Parallel Converter receives a serial data stream from the NRZI to NRZ converter, and converts the data stream to parallel data to be presented to the descrambler.

#### 7.2.2.7 Descrambler

Because the scrambling process requires to control the radiated emissions of transmit data streams, the receiver must descramble the receive data streams. The descrambler receives scrambled parallel data streams from the Serial to Parallel converter, descrambles the data streams, and presents the data streams to the Code Group alignment block.

#### 7.2.2.8 Code Group Alignment

The Code Group Alignment block receives un-aligned 5B data from the descrambler and converts it into 5B code group data. Code Group Alignment occurs after the J/K is detected, and subsequent data is aligned on a fixed boundary.

#### 7.2.2.9 4B5B Decoder

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The 4B5B Decoder functions as a look-up table that translates incoming 5B code groups into 4B (Nibble) data. When receiving a frame, the first 2 5-bit code groups received are the start-of-frame delimiter (J/K symbols). The J/K symbol pair is stripped and two nibbles of preamble pattern are substituted. The last two code groups are the end-of-frame delimiter (T/R symbols).

The T/R symbol pair is also stripped from the nibble presented to the Reconciliation layer.

#### 7.2.3 10Base-T Operation

The 10Base-T transceiver is IEEE 802.3u compliant. When the DM9161A is operating in 10Base-T mode, the coding scheme is Manchester. Data processed for transmit is presented to the MII interface in nibble format, converted to a serial bit stream, then Manchester encoded. When receiving, the Manchester encoded bit stream is decoded and converted into nibble format for presentation to the MII interface.

#### 7.2.4 Collision Detection

For half-duplex operation, a collision is detected when the transmit and receive channels are active simultaneously. When a collision has been detected, it will be reported by the COL signal on the MII interface. Collision detection is disabled in Full Duplex operation.

#### 7.2.5 Carrier Sense

Carrier Sense (CRS) is asserted in half-duplex operation during transmission or reception of data. During full-duplex mode, CRS is asserted only during receive operations.

#### 7.2.6 Auto-Negotiation

The objective of Auto-negotiation is to provide a means to exchange information between segment linked devices and to automatically configure both devices to take maximum advantage of their abilities. It is important to note that Auto-negotiation does not test the link segment characteristics. The Auto-Negotiation function provides a means for a device to advertise supported modes of operation to a remote link partner, acknowledge the receipt and understanding of common modes of operation, and to reject un-shared modes of operation. This allows devices on both ends of a segment to establish a link at the best common mode of operation. If more than one common mode exists between the two devices, a mechanism is provided to allow the devices to resolve to a single mode of operation using a predetermined priority resolution function.

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#### **Auto-Negotiation** (continued)

Auto-negotiation also provides a parallel detection function for devices that do not support the Auto-negotiation feature. During Parallel detection there is no exchange of configuration information, instead, the receive signal is examined. If it is discovered that the signal matches a technology, supported by the receiving device, a connection will be automatically established using that technology. This allows devices, which do not support Auto-negotiation but support a common mode of operation, to establish a link.

#### 7.2.7 MII Serial Management

The MII serial management interface consists of a data interface, basic register set, and a serial management interface to the register set. Through this interface it is possible to control and configure multiple PHY devices, get status and error information, and determine the type and capabilities of the attached PHY device(s).

The DM9161A management functions correspond to MII specification for IEEE 802.3u-1995 (Clause 22) for registers 0 through 6 with vendor-specific registers 16,17, 18, 21, 22, 23 and 24.

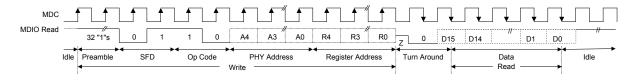
In read/write operation, the management data frame is 64-bits long and starts with 32 contiguous logic one bits (preamble) synchronization clock cycles on MDC. The Start of Frame Delimiter (SFD) is indicated by a <01> pattern followed by the operation code (OP):<10> indicates Read operation and <01> indicates Write operation. For read operation, a 2-bit turnaround (TA) filing between Register Address field and Data field is provided for MDIO to avoid contention. Following the turnaround time, 16-bit data is read from or written onto management registers.

#### 7.2.8 Serial Management Interface

The serial control interface uses a simple two-wired serial interface to obtain and control the status of the physical layer through the MII interface. The serial control interface consists of MDC (Management Data Clock), and MDI/O (Management Data Input/Output) signals.

The MDIO pin is bi-directional and may be shared by up to 32 devices.

#### 7.2.9 Management Interface - Read Frame Structure



#### 7.2.10 Management Interface - Write Frame Structure

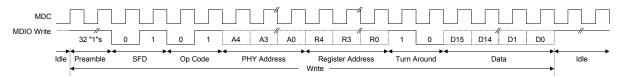


Figure 7-5

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#### 7.2.11 Power Reduced Mode

The Signal detect circuit is always turned on to monitor whether there is any signal on the media. In case of cable disconnection,, DM9161A will automatically turn off the power and enter the Power Reduced mode, regardless of its operation mode being N-way auto-negotiation or forced mode. While in the Power Reduced mode, the transmit circuit will continue sending out fast link pulse with minimum power consumption. If a valid signal is detected from the media, which might be N-way fast link pulse, 10Base-T normal link pules, or 100Base-TX MLT3 signals, the device wakes up and resumes normal operation mode.

Automatic reduced power down mode can be disabled by writing Zero to Reg.16.4.

#### 7.2.12 Power Down Mode

Power Down mode is entered by setting Reg.0.11 to ONE or pulling PWRDWN pin high, which disables all transmit and receive functions, and MII interface functions except the MDC/MDIO management interface.

#### 7.2.13 Reduced Transmit Power Mode

Additional transmit power reduction can be gained by designing with 1.25:1 turns ration magnetic on its TX side and using a  $8.5 \text{K}\Omega$  resistor on BGRES and BGRESG pins, and the TX+/TX- pulled high resistors being changed from  $50\Omega$  to  $78\Omega$ . This configuration could reduce about 20% of transmit power.

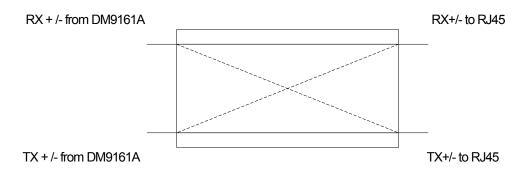
#### 7.3 HP Auto-MDIX Functional Description

The DM9161A supports the automatic detect cable connection type, MDI/MDIX (straight through/cross over). A manual configuration by register bit for MDI or MDIX is still accepted.

When set to automatic, the polarity of MDI/MDIX controlled timing is generated by a 16-bits LFSR. The switching cycle time is located from 200ms to 420ms. The polarity control is always switch until detect received signal. After selected MDI or MDIX, the polarity status can be read by register bit (20.7).(See page33,8.12 specified config register-20 bit 7)7.3.1 Function Setting. Pin 39 is used to enable HP Auto-MDIX function.

Pull pin 39 low will enable it, and pull pin 39 high will disable it.

Specified config Register 20 bit 4 (20, 4) is used by programmer to disable HP Auto-MDIX function. Write register 20 bit 4 to "1" will disable HP Auto-MDIX function. Its default value is "0". When the register 20 bit 4 (20, 4) is set to "1", the register 20 bit 5(20, 5) is used to select straight through or cross over mode, "0" is for straight through, and "1" is for cross over.



*	MDI:									
*	MDIX	_	_	_	_	_	_	_	_	_

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This feature is able to detect the required cable connection type.( straight through or crossed over ) and make correction automatically

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## 8. MII Register Description

AD D	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
00	CONTROL	Reset	Loop back	Speed select	Auto-N Enable	Power Down	Isolate	Restart Auto-N	Full Duplex	Coll. Test				Reserved	t		
	•	0	0	1	1	0	0	0	1	0				000 0000	)		
01	STATUS	T4	TXFDX	TX HDX	10 FDX	10 HDX		Rese	erved		Pream.	Auto-N	Remote	Auto-N	Link	Jabber	Extd
		Cap.	Cap.	Cap.	Cap.	Cap.					Supr.	Compl.	Fault	Сар.	Status	Detect	Cap.
		0	1	1	1	1		00	00		1	0	0	1	0	0	1
02	PHYID1	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	1
03	PHYID2	1	0	1	1	1	0			Model No.					Version No.		
										01010					0000		
04	Auto-Neg.	Next	FLP Rcv	Remote	Rese	rved	FC	T4	TX FDX	TX HDX	10 FDX	10 HDX		Advertised	Protocol Se	elector Field	
05	Advertise	Page	Ack	Fault	D	d	Adv	Adv LP	Adv I P	Adv I P	Adv I P	Adv I P		i-l-D-d	- D4I O	-1t Ti-l	_
05	Link Part. Abilitv	LP Next	LP Ack	LP RF	Rese	rvea	LP FC	T4	TX FDX	TX HDX	10 FDX		L	ink Partne	r Protocol S	elector Fiel	a
	Ability	Page	ACK	ri-			FC	14	IVLDV	IVUDV	IUFDX	10 HDX					
06	Auto-Neg.	i age	J				Reserved					l .	Pardet	LP Next	Next Pg	New Pa	LP AutoN
	Expansion						1 10001 100						Fault	Pg Able	Able	Rcv	Cap.
16	Specified	BP	BP	BP	BP_ADP	Repeater	TX	FEF_EN	RMII_E	Force	TST_SE	LEDCO	RPDCTR	Reset	Pream.	Sleep	Remote
	Config.	4B5B	SCR	ALIGN	ŌK				N	100LNK	L0	L_SEL	-EN	St. Mch	Supr.	mode	LoopOut
17	Specified	100	100	10	10 HDX	Reserve	Reverse	Reverse		PH	YADDR	[4:0]			Auto-N. Moi	nitor Bit [3:0	]
	Conf/Stat	FDX	HDX	FDX		d	d	d									
18	10T	Rsvd	LP	HBE	SQUE	JAB	10T					Reserve	d				Polarity
	Conf/Stat		Enable	Enable	Enable	Enable	Serial										Reverse
19	PWDOR				Reserved	i			PD10D V	R PD100	)I PDchi	p PDcm	n PDaeq	PDdrv	PDecli	PDedo	PD10
20	Specified	TSTSE	1 TSTSE2	EODCE	FORCE	1	Doc	served		MDIX	C AutoN	eg Mdix 1	in Main de	n ManCal	1 MonSel0	Rmii acc	PD valu
20	config	ISISE	1 1313E2	TXSD	FEF	1	Res	serveu		NTL	dlpb			J WONSE	I WOISEK	RIIII_au	e PD_valu
04	·	1-4 -4-	D			Estra secol		diate ass	le let eeel					- 011-	a lala de a	-	_
21	MDINTR	Int_sts	Reserve d	Reserve d	Reverse d	Fax_ms	Spa_msi	K LNK_ms	k Int_ms	k Reserv	e Resen	/e Revers	se Fdx_ch	g Spa_cn	g Lnk_chg	Reserve	Int_sts
			u	u	u				1		_	u				u	
22	RCVER	Receiver Error Counter															
23	DIS_connec	Reversed									Disconn	ect_counte	er				
	t																
24	RSTLH	Lh_led_ mode	_ Lh_mdint	Lh_cabst s	Lh_isolat e	Lh_mii	Lh_seril1	Lh_repe	a Lh_testr	m Lh_opi	2 Lh_op	1 Lh_op	0 Lh_phya	a Lh_phy	a Lh_phya d2	Lh_phya	Lh_phya d0
		mode		3	C		Ŭ	lCi	ouc				u +	uo	uz.	uı	uo

#### **Key to Default**

In the register description that follows, the default column takes the form:

<Reset Value>, <Access Type> / <Attribute(s)>

Where:

<Reset Value>:

Bit set to logic oneBit set to logic zeroNo default value

(PIN#) Value latched in from pin # at reset

<Access Type>:

RO = Read only

RW = Read/Write

<Attribute (s)>:

SC = Self clearing

P = Value permanently set

LL = Latching low

LH = Latching high

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# 8.1 Basic Mode Control Register (BMCR) - 00

Bit	Bit Name	Default	Description
0.15	Reset	0, RW/SC	Reset
			1=Software reset
			0=Normal operation
			This bit sets the status and controls the PHY registers to their default
			states. This bit, which is self-clearing, will keep returning a value of
0.44	l a a a la a a la	0. DW	one until the reset process is completed
0.14	Loopback	0, RW	Loopback
			Loop-back control register 1 = Loop-back enabled
			0 = Normal operation
			When in 100Mbps operation mode, setting this bit may cause the
			descrambler to lose synchronization and produce a 720ms "dead
			time" before any valid data appears at the MII receive outputs
0.13	Speed selection	1, RW	Speed Select
0110		.,	1 = 100Mbps
			0 = 10Mbps
			Link speed may be selected either by this bit or by auto-negotiation.
			When auto-negotiation is enabled and bit 12 is set, this bit will return
			auto-negotiation selected medium type
0.12	Auto-negotiation	1, RW	Auto-negotiation Enable
	enable		1 = Auto-negotiation is enabled, bit 8 and 13 will be in
			auto-negotiation status
0.11	Power down	0, RW	Power Down
			While in the power-down state, the PHY should respond to
			management transactions. During the transition to power-down state
			and while in the power-down state, the PHY should not generate spurious signals on the MII
			1=Power down
			0=Normal operation
0.10	Isolate	0,RW	Isolate
0.10	1001410	0,1111	1 = Isolates the DM9161A from the MII with the exception of the serial
			management. (When this bit is asserted, the DM9161A does not
			respond to the TXD [0:3], TX_EN, and TX_ER inputs, and it shall
			present a high impedance on its TX_CLK, RX_CLK, RX_DV,
			RX_ER, RXD[0:3], COL and CRS outputs. When PHY is isolated
			from the MII it shall respond to the management transactions)
			0 = Normal operation
0.9	Restart	0,RW/SC	Restart Auto-negotiation
	Auto-negotiation		1 = Restart auto-negotiation. Re-initiates the auto-negotiation
			process. When auto-negotiation is disabled (bit 12 of this register
			cleared), this bit has no function and it should be cleared. This bit is
			self-clearing and it will keep returning to a value of 1 until auto-negotiation is initiated by the DM9161A. The operation of the
			auto-negotiation process will not be affected by the management
			entity that clears this bit
			0 = Normal operation
			U - Normai operation

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0.8	Duplex mode	1,RW	Duplex Mode 1 = Full duplex operation. Duplex selection is allowed when Auto-negotiation is disabled (bit 12 of this register is cleared). With auto-negotiation enabled, this bit reflects the duplex capability selected by auto-negotiation 0 = Normal operation
0.7	Collision test	0,RW	Collision Test  1 = Collision test enabled. When set, this bit will cause the COL signal to be asserted in response to the assertion of TX_EN  0 = Normal operation
0.6-0.0	Reserved	0,RO	Reserved Read as 0, ignore on write

## 8.2 Basic Mode Status Register (BMSR) - 01

Bit	Bit Name	Default	Description
1.15	100BASE-T4	0,RO/P	100BASE-T4 Capable
	.002/102	0,1.07.	1 = DM9161A is able to perform in 100BASE-T4 mode
			0 = DM9161A is not able to perform in 100BASE-T4 mode
1.14	100BASE-TX	1,RO/P	100BASE-TX Full Duplex Capable
	full-duplex	.,	1 = DM9161A is able to perform 100BASE-TX in full duplex mode
			0 = DM9161A is not able to perform 100BASE-TX in full duplex mode
1.13	100BASE-TX	1,RO/P	100BASE-TX Half Duplex Capable
	half-duplex	, -	1 = DM9161A is able to perform 100BASE-TX in half duplex mode
			0 = DM9161A is not able to perform 100BASE-TX in half duplex
			mode
1.12	10BASE-T	1,RO/P	10BASE-T Full Duplex Capable
	full-duplex		1 = DM9161A is able to perform 10BASE-T in full duplex mode
	•		0 = DM9161A is not able to perform 10BASE-TX in full duplex mode
1.11	10BASE-T	1,RO/P	10BASE-T Half Duplex Capable
	half-duplex		1 = DM9161A is able to perform 10BASE-T in half duplex mode
	·		0 = DM9161A is not able to perform 10BASE-T in half duplex mode
1.10-1.7	Reserved	0,RO	Reserved
			Read as 0, ignore on write
1.6	MF preamble	1,RO	MII Frame Preamble Suppression
	suppression		1 = PHY will accept management frames with preamble suppressed
			0 = PHY will not accept management frames with preamble
			suppressed
1.5	Auto-negotiation	0,RO	Auto-negotiation Complete
	Complete		1 = Auto-negotiation process completed
			0 = Auto-negotiation process not completed
1.4	Remote fault	0, RO/LH	Remote Fault
			1 = Remote fault condition detected (cleared on read or by a chip
			reset). Fault criteria and detection method is DM9161A
			implementation specific. This bit will set after the RF bit in the
			ANLPAR (bit 13, register address 05) is set
			0 = No remote fault condition detected
1.3	Auto-negotiation	1,RO/P	Auto Configuration Ability
	ability		1 = DM9161A is able to perform auto-negotiation
			0 = DM9161A is not able to perform auto-negotiation
1.2	Link status	0,RO/LL	Link Status
			1 = Valid link is established (for either 10Mbps or 100Mbps operation)

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# 10/100 Mbps Fast Ethernet Physical Layer Single Chip Transceiver

			, , , , , , , , , , , , , , , , , , , ,
			0 = Link is not established The link status bit is implemented with a latching function, so that the occurrence of a link failure condition causes the link status bit to be cleared and remain cleared until it is read via the management interface
1.1	Jabber detect	0, RO/LH	Jabber Detect 1 = Jabber condition detected 0 = No jabber This bit is implemented with a latching function. Jabber conditions will set this bit unless it is cleared by a read to this register through a management interface or a DM9161A reset. This bit works only in 10Mbps mode
1.0	Extended capability	1,RO/P	Extended Capability 1 = Extended register capable 0 = Basic register capable only

## 8.3 PHY ID Identifier Register #1 (PHYID1) - 02

The PHY Identifier Registers #1 and #2 work together in a single identifier of the DM9161A. The Identifier consists of a concatenation of the Organizationally Unique Identifier (OUI), a vendor's model number, and a model revision number. DAVICOM Semiconductor's IEEE assigned OUI is 00606E.

Bit	Bit Name	Default	Description
2.15-2.0	OUI_MSB	<0181h>	OUI Most Significant Bits
			This register stores bit 3 to 18 of the OUI (00606E) to bit 15 to 0 of
			this register respectively. The most significant two bits of the OUI
			are ignored (the IEEE standard refers to these as bit 1 and 2)

# 8.4 PHY ID Identifier Register #2 (PHYID2) - 03

Bit	Bit Name	Default	Description
3.15-3.10	OUI_LSB	<101110>,	OUI Least Significant Bits
		RO/P	Bit 19 to 24 of the OUI (00606E) are mapped to bit 15 to 10 of this
			register respectively
3.9-3.4	VNDR_MDL	<001010>,	Vendor Model Number
		RO/P	Five bits of vendor model number mapped to bit 9 to 4 (most
			significant bit to bit 9)
3.3-3.0	MDL_REV	<0000>,	Model Revision Number
		RO/P	Five bits of vendor model revision number mapped to bit 3 to 0
			(most significant bit to bit 4)

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## 8.5 Auto-negotiation Advertisement Register (ANAR) - 04

This register contains the advertised abilities of this DM9161A device as they will be transmitted to its link partner during Auto-negotiation.

Bit	Bit Name	Default	Description
4.15	NP	0,RO/P	Next page Indication
			0 = No next page available
			1 = Next page available
			The DM9161A has no next page, so this bit is permanently set to 0
4.14	ACK	0,RO	Acknowledge
			1 = Link partner ability data reception acknowledged
			0 = Not acknowledged
			The DM9161A's auto-negotiation state machine will automatically
			control this bit in the outgoing FLP bursts and set it at the
			appropriate time during the auto-negotiation process. Software
			should not attempt to write to this bit.
4.13	RF	0, RW	Remote Fault
			1 = Local device senses a fault condition
			0 = No fault detected
4.12-4.11	Reserved	X, RW	Reserved
			Write as 0, ignore on read
4.10	FCS	0, RW	Flow Control Support
			1 = Controller chip supports flow control ability
			0 = Controller chip doesn't support flow control ability
4.9	T4	0, RO/P	100BASE-T4 Support
			1 = 100BASE-T4 is supported by the local device
			0 = 100BASE-T4 is not supported
			The DM9161A does not support 100BASE-T4 so this bit is
			permanently set to 0
4.8	TX_FDX	1, RW	100BASE-TX Full Duplex Support
			1 = 100BASE-TX full duplex is supported by the local device
			0 = 100BASE-TX full duplex is not supported
4.7	TX_HDX	1, RW	100BASE-TX Support
			1 = 100BASE-TX half duplex is supported by the local device
1.0	10. 5517	4.504	0 = 100BASE-TX half duplex is not supported
4.6	10_FDX	1, RW	10BASE-T Full Duplex Support
			1 = 10BASE-T full duplex is supported by the local device
1.5	40 1107	4 514/	0 = 10BASE-T full duplex is not supported
4.5	10_HDX	1, RW	10BASE-T Support
			1 = 10BASE-T half duplex is supported by the local device
1110	0 1 1	200004 511	0 = 10BASE-T half duplex is not supported
4.4-4.0	Selector	<00001>, RW	Protocol Selection Bits
			These bits contain the binary encoded protocol selector supported
			by this node
			<00001> indicates that this device supports IEEE 802.3 CSMA/CD

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# 8.6 Auto-negotiation Link Partner Ability Register (ANLPAR) - 05

This register contains the advertised abilities of the link partner when received during Auto-negotiation.

Bit	Bit Name	Default	Description
5.15	NP	0, RO	Next Page Indication
			0 = Link partner, no next page available
			1 = Link partner, next page available
5.14	ACK	0, RO	Acknowledge
			1 = Link partner ability data reception acknowledged
			0 = Not acknowledged
			The DM9161A's auto-negotiation state machine will automatically
			control this bit from the incoming FLP bursts. Software should not
			attempt to write to this bit
5.13	RF	0, RO	Remote Fault
			1 = Remote fault indicated by link partner
			0 = No remote fault indicated by link partner
5.12-5.11	Reserved	0, RO	Reserved
			Read as 0, ignore on write
5.10	FCS	0, RO	Flow Control Support
			1 = Controller chip supports flow control ability by link partner
			0 = Controller chip doesn't support flow control ability by link partner
5.9	T4	0, RO	100BASE-T4 Support
			1 = 100BASE-T4 is supported by the link partner
			0 = 100BASE-T4 is not supported by the link partner
5.8	TX_FDX	0, RO	100BASE-TX Full Duplex Support
			1 = 100BASE-TX full duplex is supported by the link partner
			0 = 100BASE-TX full duplex is not supported by the link partner
5.7	TX_HDX	0, RO	100BASE-TX Support
			1 = 100BASE-TX half duplex is supported by the link partner
			0 = 100BASE-TX half duplex is not supported by the link partner
5.6	10_FDX	0, RO	10BASE-T Full Duplex Support
			1 = 10BASE-T full duplex is supported by the link partner
			0 = 10BASE-T full duplex is not supported by the link partner
5.5	10_HDX	0, RO	10BASE-T Support
			1 = 10BASE-T half duplex is supported by the link partner
			0 = 10BASE-T half duplex is not supported by the link partner
5.4-5.0	Selector	<00000>, RO	Protocol Selection Bits
			Link partner's binary encoded protocol selector

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# 8.7 Auto-negotiation Expansion Register (ANER)- 06

Bit	Bit Name	Default	Description
6.15-6.5	Reserved	0, RO	Reserved
			Read as 0, ignore on write
6.4	PDF	0, RO/LH	Local Device Parallel Detection Fault
			PDF = 1: A fault detected via parallel detection function.
			PDF = 0: No fault detected via parallel detection function
6.3	LP_NP_ABLE	0, RO	Link Partner Next Page Able
			LP_NP_ABLE = 1: Link partner, next page available
			LP_NP_ABLE = 0: Link partner, no next page
6.2	NP_ABLE	0,RO/P	Local Device Next Page Able
			NP_ABLE = 1: DM9161A, next page available
			NP_ABLE = 0: DM9161A, no next page
			DM9161A does not support this function, so this bit is always 0
6.1	PAGE_RX	0, RO/LH	New Page Received
			A new link code word page received. This bit will be automatically
			cleared when the register (register 6) is read by management
6.0	LP_AN_ABLE	0, RO	Link Partner Auto-negotiation Able
			A "1" in this bit indicates that the link partner supports
			Auto-negotiation

# 8.8 DAVICOM Specified Configuration Register (DSCR) - 16

Bit	Bit Name	Default	Description
16.15	BP_4B5B	0,RW	Bypass 4B5B Encoding and 5B4B Decoding
			1 = 4B5B encoder and 5B4B decoder function bypassed
			0 = Normal 4B5B and 5B4B operation
16.14	BP_SCR	0, RW	Bypass Scrambler/Descrambler Function
			1 = Scrambler and descrambler function bypassed
			0 = Normal scrambler and descrambler operation
16.13	BP_ALIGN	0, RW	Bypass Symbol Alignment Function
			1 = Receive functions (descrambler, symbol alignment and symbol
			decoding functions) bypassed. Transmit functions (symbol encoder
			and scrambler) bypassed
			0 = Normal operation
16.12	BP_ADPOK	1, RW	Bypass ADPOK
			1=Reserved
			0=Normal operation
16.11	REPEATER	(Pin#38),RW	Repeater/Node Mode
			The value of the Repeater/Node pin (38) is latched into this bit at
			power-up/reset
			1 = Repeater mode
			0 = Node mode
16.10	TX	1, RW	100BASE-TX Mode Control
			1 = 100BASE-TX operation
16.9	Reserved	1, RO	Reserved
16.8	RMII_Enable	(Pin#36), RW	Reduced MII Enable
			Select normal MII or reduced MII. The value of the RMII pin(36) is
			latched into this bit at power-up/reset
			0 = Normal MII

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			Too Mopo Table Ellicitiett Tiyoloal Eayer Olligic Oflip Transcolver
			1 = Enable Reduced MII
16.7	F_LINK_100	0, RW	Force Good Link in 100Mbps
			0 = Normal 100Mbps operation
			1 = Force 100Mbps good link status
			This bit is useful for diagnostic purposes
16.6	SPLED_CTL	0, RW	Speed LED Disable
			0 = Normal SPEEDLED output to indicate speed status
			1 = Disable SPEEDLED output
16.5	COLLED_CTL	0, RW	Collision LED Enable
			0 = FDX/COLLED output is configured to indicate Full/half duplex
			status
			1 = FDX/COLLED output is configured to indicate
			Full-duplex/Collision status
16.4	RPDCTR-EN	1, RW	Reduced Power Down Control Enable
			This bit is used to enable automatic reduced power down
			0 = Disable automatic reduced power down
			1 = Enable automatic reduced power down
16.3	SMRST	0, RW	Reset State Machine
		,	When writes 1 to this bit, all state machines of PHY will be reset.
			This bit is self-clear after reset is completed
16.2	MFPSC	1, RW	MF Preamble Suppression Control
		,	MII frame preamble suppression control bit
			1 = MF preamble suppression bit on
			0 = MF preamble suppression bit off
16.1	SLEEP	0, RW	Sleep Mode
		,	Writing a 1 to this bit will cause PHY entering the Sleep mode and
			power down all circuit except oscillator and clock generator circuit.
			When waking up from Sleep mode (write this bit to 0), the
			configuration will go back to the state before sleep; but the state
			machine will be reset
16.0	RLOUT	0, RW	Remote Loopout Control
		,	When this bit is set to 1, the received data will loop out to the
			transmit channel. This is useful for bit error rate testing

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# 8.9 DAVICOM Specified Configuration and Status Register (DSCSR) - 17

Bit	Bit Name	Default					Description
17.15	100FDX	1, RO	bit is 1, it mea software can r	otiat ns th ead	tion ne op bit [	is co perat 15:1	mpleted, results will be written to this bit. If this ion 1 mode is a 100M full duplex mode. The 2] to see which mode is selected after
			auto-negotiation	on. T	his	bit is	invalid when it is not in the auto-negotiation
17.14	100HDX	1, RO	100M Half Du After auto-neg bit is 1, it mea software can r	otiat ns th	tion ne o <sub>l</sub> bit [	is co perat 15:1	on Mode mpleted, results will be written to this bit. If this tion 1 mode is a 100M half duplex mode. The 2] to see which mode is selected after invalid when it is not in the auto-negotiation
17.13	10FDX	1, RO	bit is 1, it mea software can r auto-negotiation mode	otiat ns the ead on. T	tion ne op bit [ This	is co perat 15:1: bit is	mpleted, results will be written to this bit. If this ion 1 mode is a 10M Full Duplex mode. The 2] to see which mode is selected after invalid when it is not in the auto-negotiation
17.12	10HDX	1, RO	bit is 1, it mea software can r	otiat ns the	tion ne op bit [	is co perat 15:1	Mode mpleted, results will be written to this bit. If this ion 1 mode is a 10M half duplex mode. The 2] to see which mode is selected after invalid when it is not in the auto-negotiation
17.11-17. 9	Reserved	0, RO	Reserved Read as 0, igr	nore	on v	vrite	
	PHYADR[4	(PHYADR),	PHY Address			******	
	:0]	RW	The first PHY (bit 4). A static	addr on m	ess ana	geme	ansmitted or received is the MSB of the address ent entity connected to multiple PHY entities address of each PHY
17.3-17.0	ANMB[3:0]	0, RO	Auto-negotiati	on M	1onit	or B	
17.3-17.0	ANMB[3:0]	0, RO	Auto-negotiati These bits are these bits.				its nly.The auto-negotiation status will be written to
			B3	b2	b1	B0	
			0	0	0	0	In IDLE state
			0	0	0	1	Ability match
			0	0	1	0	Acknowledge match
			0	0	1	1	Acknowledge match fail
			0	1	0	0	Consistency match foil
			0	1	<u>0</u>	0	Consistency match fail
			0	1	1	1	Parallel detects signal_link_ready Parallel detects signal_link_ready fail
			1	0	0	0	Auto-negotiation completed successfully
				-		-	

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# 8.10 10BASE-T Configuration/Status (10BTCSR) - 18

Bit	Bit Name	Default	Description
18.15	Reserved	0, RO	Reserved
			Read as 0, ignore on write
18.14	LP_EN	1, RW	Link Pulse Enable
			1 = Transmission of link pulses enabled
			0 = Link pulses disabled, good link condition forced
			This bit is valid only in 10Mbps operation
18.13	HBE	1,RW	Heartbeat Enable
			1 = Heartbeat function enabled
			0 = Heartbeat function disabled
			When the DM9161A is configured for full duplex operation, this bit will
			be ignored (the collision/heartbeat function is invalid in full duplex mode)
18.12	SQUELCH	1, RW	Squelch Enable
			1 = Normal squelch
			0 = Low squelch
18.11	JABEN	1, RW	Jabber Enable
			Enables or disables the Jabber function when the DM9161A is in
			10BASE-T full duplex or 10BASE-T transceiver loopback mode
			1 = Jabber function enabled
			0 = Jabber function disabled
18.10	10BT_SER	(#PIN	10BASE-T GPSI Mode ( Default value depend on #pin34 strap
		34),RW	condition)
			1 = 10BASE-T GPSI mode selected (#pin34 pull down)
			0 = 10BASE-T MII mode selected (#pin34 pull up, default)
10.0.10.1			GPSI mode is not supported for 100Mbps operation
18.9-18.1	Reserved	0, RO	Reserved
10.0	DOI D	0.00	Read as 0, ignore on write
18.0	POLR	0, RO	Polarity Reversed
			When this bit is set to 1, it indicates that the 10Mbps cable polarity is
			reversed. This bit is automatically set and cleared by 10BASE-T module

# 8.11 Power Down Control Register (PWDOR) - 19

Bit	Bit Name	Default	Description
19.15-19.9	Reserved	0, RO	Reserved
			Read as 0, ignore on write
19.8	PD10DRV	0, RW	Vendor powerdown control test
19.7	PD100DL	0, RW	Vendor powerdown control test
19.6	PDchip	0, RW	Vendor powerdown control test
19.5	PDcom	0, RW	Vendor powerdown control test
19.4	PDaeq	0, RW	Vendor powerdown control test
19.3	PDdrv	0, RW	Vendor powerdown control test
19.2	PDedi	0, RW	Vendor powerdown control test
19.1	PDedo	0, RW	Vendor powerdown control test
19.0	PD10	0, RW	Vendor powerdown control test

<sup>\*</sup> when selected , the powerdown value is control by Register 20.0

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# 8.12 (Specified config) Register -20

Bit	Bit Name	Default	Description
20.15	TSTSE1	0,RW	Vendor test select control
20.14	TSTSE2	0,RW	Vendor test select control
20.13	Reserved	0, RO	Reserved
			Read as 0, ignore on write
20.12	TSTSEL3	0,RW	Vendor test select control
20.11-20.	Reserved	0, RO	Reserved
8			Read as 0, ignore on write
20.7	MDIX_CNTL	MDI/MDIX,RO	The polarity of MDI/MDIX value
			1: MDIX mode
			0: MDI mode
20.6	AutoNeg_dpbk	0,RW	Auto-negotiation loopback
			1: test internal digital auto-negotiation loopback
			0: normal.
20.5	Mdix_fix Value	0, RW	MDIX_CNTL force value:
			When MDIX_DOWN = 1, MDIX_CNTL value depend on the register
			value.
20.4	Mdix_do wn	0,RW	MDIX Down
			Manual force MDI/MDIX.
			0: Enable HP Auto-MDIX
			1: Disable HP Auto-MDIX , MDIX_CNTL value depend on 20.5
20.3	MonSel1	0,RW	Vendor monitor select
20.2	MonSel0	0,RW	Vendor monitor select
20.1	RMII_Ver	0,RW	RMII version
			0: support RMII 1.2
			1: support RMII 1.0
20.0	PD_value	0,RW	Powerdown control value
			Decision the value of each field Register 19.
			1: powerdown
			0: normal

# 8.13 DAVICOM Specified Interrupt Register – 21

Bit	Bit Name	Default	Description
21.15	INTR PEND	0, RO	Interrupt Pending
			Indicates that the interrupt is pending and is cleared by the current read. This bit shows the same result as bit 0. (INTR Status)
21.14-21. 12	Reserved	0, RO	Reserved
21.11	FDX mask	1, RW	Full-duplex Interrupt Mask When this bit is set, the Duplex status change will not generate the interrupt
21.10	SPD mask	1, RW	Speed Interrupt Mask When this bit is set, the Speed status change will not generate the interrupt
21.12	LINK mask	1, RW	Link Interrupt Mask When this bit is set, the link status change will not generate the interrupt
21.8	INTR mask	1, RW	Master Interrupt Mask When this bit is set, no interrupts will be generated under any

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			condition	
21.7-21.5	Reserved	0, RO	Reserved	
21.4	FDX change	0,RO/LH	Duplex Status Change Interrupt	
			"1" indicates a change of duplex since last register read. A read of this register will clear this bit	
21.3	SPD change	0, RO/LH	Speed Status Change Interrupt "1" indicates a change of speed since last register read. A read of this register will clear this bit	
21.2	LINK change	0, RO/LH	Link Status Change Interrupt "1" indicates a change of link since last register read. A read of this register will clear this bit	
21.1	Reserved	0, RO	Reserved	
21.0	INTR status	0, RO/LH	Interrupt Status The status of MDINTR#. "1" indicates that the interrupt mask is off that one or more of the change bits are set. A read of this register will clear this bit	

# 8.14 DAVICOM Specified Receive Error Counter Register (RECR) – 22

Bit	Bit Name	Default	Description
22.15-0	Rcv_Err_Cnt	0, RO	Receive Error Counter
			Receive error counter that increments upon detection of RXER.
			Clean by read this register.

# 8.15 DAVICOM Specified Disconnect Counter Register (DISCR) – 23

Bit	Bit Name	Default	Description
23.15-23. 8	Reserved	0, RO	Reserved
23.7-23.0	Disconnect Counter	0, RO	Disconnect Counter that increments upon detection of disconnection. Clean by read this register.

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# 8.16 DAVICOM Hardware Reset Latch State Register (RLSR) – 24

Bit	Bit Name	Default	Description
15	LH_LEDMODE	1	LEDMODE pin reset latch value
14	LH_MDINTR	1	MDINTR pin reset latch value
13	LH_CSTS	0	CABLESTS pin reset latch value
12	LH_ISO	0	TXCLK pin reset latch value
11	LH_RMII	0	COL pin reset latch value
10	LH_TP10SER	1	RXCLK pin reset latch value
9	LH_REPTR	0	RXER pin reset latch value
8	LH_TSTMOD	0	RXDV pin reset latch value
7	LH_OP2	1	LED2 pin reset latch value
6	LH_OP1	1	LED1 pin reset latch value
5	LH_OP0	1	LED0 pin reset latch value
4	LH_PH4	0	CRS pin reset latch value
3	LH_PH3	0	RXD3 pin reset latch value
2	LH_PH2	0	RXD2 pin reset latch value
1	LH_PH1	0	RXD1 pin reset latch value
0	LH_PH0	0	RXD0 pin reset latch value

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#### 9. DC and AC Electrical Characteristics

#### 9.1 Absolute Maximum Ratings (25°C)

Symbol	Parameter	Min.	Max.	Unit	Conditions
DVDD,	Supply Voltage	-0.3	3.6	V	
VIN	DC Input Voltage (Vเท)	-0.5	5.5	V	
Vout	DC Output Voltage(Vo∪T)	-0.3	3.6	V	
Tstg	Storage Temperature Rang (Tstg)	-65	+150	°C	
Tc	Case Temperature	0	85	°C	<b>@</b> Ta=0 ~ 70°C
LT	Lead Temp. (TL, Soldering, 10 sec.)	-	235	°C	DM9161AE
LT	Lead Temp. (TL, Soldering, 10 sec.)	-	260	°C	DM9161AEP

#### 9.2 Operating Conditions

Symbol	Parameter	Min.	Max.	Unit	Conditions
Dvdd	Supply Voltage	3.135	3.465	V	
TA	Ambient Temperature	0	70	°C	
Tc	Case Temperature	-	85	°C	As Ta = 70°C
PD	100BASE-TX	-	92	mA	3.3V
(Power Dissipation)	10BASE-T TX, normal activity traffic	-	72	MΑ	3.3V
	50% utility.				
	10BASE-T idle	-	25	mA	3.3V
	Auto-negotiation	-	52	MΑ	3.3V
	Power Reduced Mode (without cable )	-	25	MΑ	3.3V
	Power Down Mode	-	3.8	MA	3.3V

#### Comments

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of this device at these or any other

conditions above those indicated that in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

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## **9.3 DC Electrical Characteristics** (DVDD = 3.3V)

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
TTL Inputs	S					
(TXD0~TX	D3, TXCLK, MDC, MDIO, TXEN, TXER, F	RXEN, TE	STMODE	E, RMII, PH	IYAD0~4,	OPMODE0-2, RPTR,
RESET#	)					
VIL	Input Low Voltage	1	-	0.8	V	
VIH	Input High Voltage	2.0	-	-	V	
l⊩	Input Low Leakage Current	-	-	5	UA	VIN = 0.4V
lιΗ	Input High Leakage Current	-5	-		UA	VIN = 2.7V
Vol	Output Low Voltage	-	-	0.4	V	IOL = 4mA
Voh	Output High Voltage	2.4	-	-	V	IOH = -4mA
Receiver						
VICM	RX+/RX- Common mode Input Voltage	-	2.5	-	V	100 $\Omega$ Termination Across
Transmitte	er					
VTD100	100TX+/- Differential Output Voltage	1.9	2.0	2.1	V	Peak to Peak
VTD10	10TX+/- Differential Output Voltage	4.4	5	5.6	V	Peak to Peak
ITD100	100TX+/- Differential Output Current	19	20	21	MA	
ITD10	10TX+/- Differential Output Current	44	50	56	mA	

## 9.4 AC Electrical Characteristics & Timing Waveforms

#### 9.4.1 TP Interface

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
tTR/F	100TX+/- Differential Rise/Fall Time	3.0	-	5.0	ns	
tTM	100TX+/- Differential Rise/Fall Time Mismatch	0	-	0.5	ns	
tTDC	100TX+/- Differential Output Duty Cycle	0	-	0.5	ns	
	Distortion					
<b>t</b> ⊤/⊤	100TX+/- Differential Output Peak-to-Peak Jitter	0	-	1.4	ns	
XOST	100TX+/- Differential Voltage Overshoot	0	-	5	%	

# 9.4.2 Oscillator/Crystal Timing

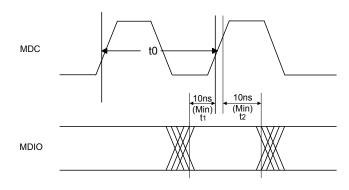
Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
	OSC Frag	24.998	25	25.001	mhz	50ppm
tckc	OSC Cycle Time	39.998	40	40.002	ns	50ppm
tPWH	OSC Pulse Width High	16	20	24	ns	
tPWL	OSC Pulse Width Low	16	20	24	ns	

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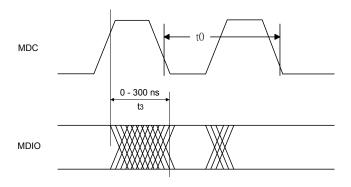
## 9.4.3 MDC/MDIO Timing

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
to	MDC Cycle Time	80	-	-	ns	
t1	MDIO Setup Before MDC	10	-	-	ns	When OUTPUT By STA
t2	MDIO Hold After MDC	10	-	-	ns	When OUTPUT By STA
t3	MDC To MDIO Output Delay	0	-	300	ns	When OUTPUT By DM9161A

# 9.4.4 MDIO Timing When OUTPUT by STA



# 9.4.5 MDIO Timing When OUTPUT by DM9161A



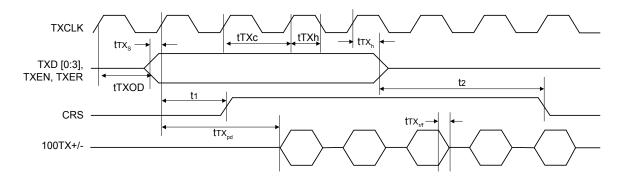
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## 9.4.6 100BASE-TX Transmit Timing Parameters

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
t⊤xc	TXCLK Cycle Time	39.998	40	40.002	ns	50ppm
ttxh, ttxi	TXCLK High/Low Time	16	20	24	ns	
tTX <sub>s</sub>	TXD [0:3], TXEN, TXER Setup To TXCLK High	12	-	-	ns	
tTX <sub>h</sub>	TXD [0:3], TXEN, TXER Hold From TXCLK High	0	-	-	ns	
ttxod	TXCLK to Output Delay			25	ns	
t1	TXEN Sampled To CRS Asserted	-	4	-	BT	
t2	TXEN Sampled To CRS De-asserted	-	4	-	BT	
tTX <sub>pd</sub>	TXEN Sampled To TX+/- Out (Tx Latency)	-	8	-	BT	
tTX <sub>r/f</sub>	100TX Driver Rise/Fall Time	3	4	5	ns	90% To 10%, Into 100ohm Differential
Note 1		only; not gu	uaranteed	and not s	ubject to	production testing.

# 9.4.7 100BASE-TX Transmit Timing Diagram



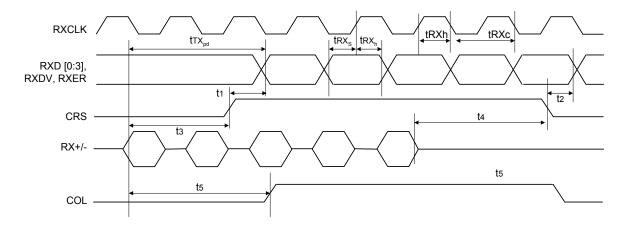
# 9.4.8 100BASE-TX Receive Timing Parameters

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
tRXc	RXCLK Cycle Time	39.998	40	40.002		50ppm
TRXh, tRXI	RXCLK High/Low Time	16	20	24		
trx <sub>s</sub>	RXD [0:3], RXDV, RXER Setup To RXCLK High	10	-	-	ns	
t <sub>RX</sub> <sub>h</sub>	RXD [0:3], RXDV, RXER Hold From RXCLK High	10	-	-	ns	
tRX <sub>pd</sub>	RX+/- In To RXD [0:3] Out (Rx Latency)	-	15	-	BT	
t1	CRS Asserted To RXD [0:3], RXDV, RXER	-	4	-	BT	
t2	CRS De-asserted To RXD [0:3], RXDV, RXER	-	0	-	BT	
t3	RX+/- In To CRS Asserted	10	-	14	BT	
t4	RX+/- Quiet To CRS De-asserted	14	-	18	BT	
t5	RX+/- In To COL De-Asserted	14	-	18	BT	
1. Typical va	alues are at 25°C and are for design aid only; not guaranteed	and not s	ubject to	oroduction	testing.	

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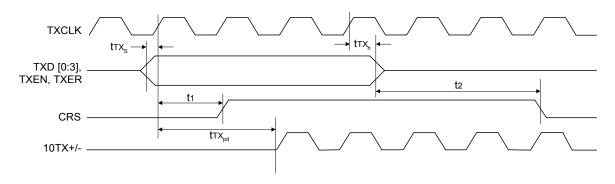
## 9.4.9 MII 100BASE-TX Receive Timing Diagram



# 9.4.10 MII 10BASE-T Nibble Transmit Timing Parameters

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
tTX <sub>s</sub>	TXD[0:3), TXEN, TXER Setup To TXCLK High	5	-	-	ns	
tTX <sub>h</sub>	TXD[0:3], TXEN, TXER Hold From TXCLK High	5	-	-	ns	
t1	TXEN Sampled To CRS Asserted	-	2	4	BT	
t2	TXEN Sampled To CRS De-asserted	-	15	20	BT	
tTX <sub>pd</sub>	TXEN Sampled To 10TXO Out (Tx Latency)	-	2	4	BT	

## 9.4.11 MII 10BASE-T Nibble Transmit Timing Diagram



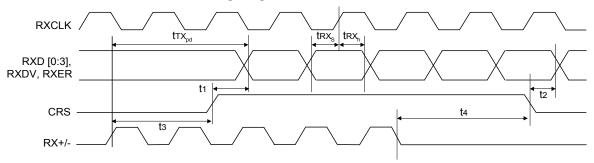
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## 9.4.12 MII 10BASE-T Receive Nibble Timing Parameters

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
trx <sub>s</sub>	RXD [0:3], RXDV, RXER Setup To RXCLK High	5	1	-	ns	
tRX <sub>h</sub>	RXD [0:3], RXDV, RXER Hold From RXCLK High	5	-	-	ns	
tRX <sub>pd</sub>	RX+/- To RXD [0:3] Out (Rx Latency)	-	7	-	BT	
t1	CRS Asserted To RXD [0:3], RXDV, RXER, Asserted	1	14	20	BT	
t2	CRS De-asserted To RXD [0:3], RXDV,	-	-	3	BT	
	RXER,De-asserted					
t3	RXI In To CRS Asserted	1	2	4	BT	
t4	RXI Quiet To CRS De-asserted	1	10	15	BT	

## 9.4.13 MII 10BASE-T Receive Nibble Timing Diagram



## 9.4.14 Auto-negotiation and Fast Link Pulse Timing Parameters

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
t1	Clock/Data Pulse Width	-	100	ı	ns	
t2	Clock Pulse To Data Pulse Period	55.5	62.5	69.5	us	DATA = 1
t3	Clock Pulse To Clock Pulse Period	111	125	139	us	
t4	FLP Burst Width	-	2	-	ms	
t5	FLP Burst To FLP Burst Period	8	-	24	ms	
-	Clock/Data Pulses in a Burst	17	-	33	pulse	

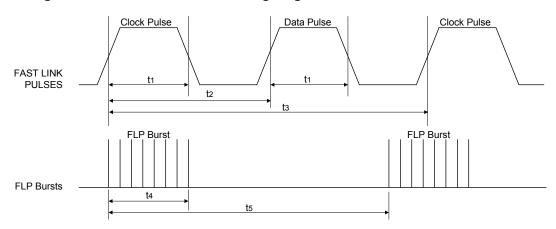
Version: DM9161A-DS-F01

October 16, 2009

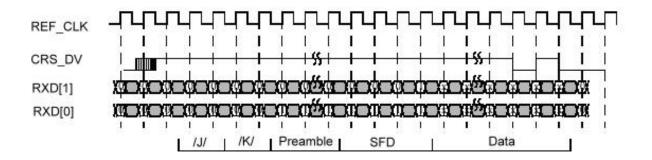
Final



## 9.4.15 Auto-negotiation and Fast Link Pulse Timing Diagram

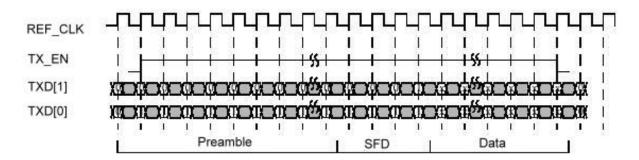


#### 9.4.16 RMII Receive Timing Diagram



100 Mb/s Reception with no errors

#### 9.4.17 RMII Transmit Timing Diagram



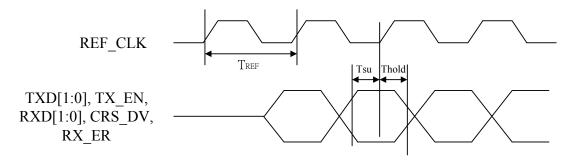
100 Mb/s Transmission

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#### 9.4.18 RMII Timing Diagram



## 9.4.19 RMII Timing Parameter

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
Fref	REF_CLK Frequency	49.9985	50	50.0015	MHz	30ppm (1.5KHZ)
Tref%	REF_CLK Duty Cycle	35	-	65	%	,
Tref	REF_CLK Clock Cycle		20	-	ns	30ppm
Tsu	TXD[1:0], TX_EN, RXD[1:0], CRS_DV, RX_ER Data Setup to REF_CLK rising edge	4	-	-	ns	
Thold	TXD[1:0], TX_EN, RXD[1:0], CRS_DV, RX_ER Data hold from REF_CLK rising edge	2	-	-	ns	

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# 9.4.20 Magnetics Selection Guide

Refer to Table 2 for transformer requirements. Transformers, meeting these requirements, are available from a variety of magnetic manufacturers. Designers should test and qualify all magnetics before using them in an application. The transformers listed in Table 2 are electrical equivalents, but may not be pin-to-pin equivalents.

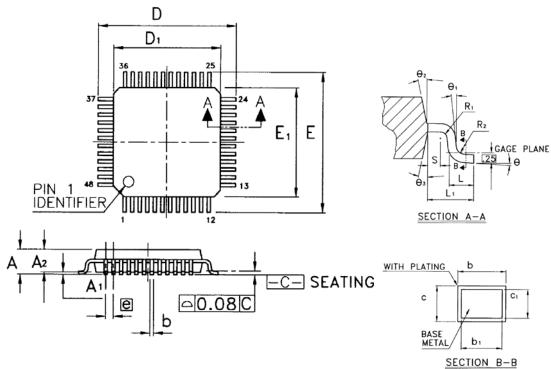
Manufacturer	Part Number			
Pulse Engineering	PE-68515, H1078, H1012, H1102			
Delta	LF8200, LF8221x			
YCL	20PMT04, 20PMT05, PH163112, YCL 0303			
	PH163539 *(HP Auto-MDIX)			
Halo	TG22-3506ND, TD22-3506G1, TG22-S010ND, TG22-S012ND			
	TG110-S050N2			
Nano Pulse Inc.	NPI 6181-37, NPI 6120-30, NPI 6120-37			
	NPI 6170-30			
Fil-Mag	PT41715			
Bel Fuse	S558-5999-01, S558-5999-W2			
Valor	ST6114, ST6118			
Macronics	HS2123, HS2213			
Bothhand	TS6121C,16ST8515,16ST1086			

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# 10. Package Information

48 Pins LQFP Package Outline Information:



	Dimension in mm				Dimension in inch		
Symbol	Min	Nom	Max	1	Min	Nom	Max
Α	-	-	1.60		-	-	0.063
A <sub>1</sub>	0.05	-	0.15		0.002	-	0.006
$A_2$	1.35	1.40	1.45		0.053	0.055	0.057
b	0.17	0.22	0.27		0.007	0.009	0.011
b <sub>1</sub>	0.17	0.20	0.23		0.007	0.008	0.009
С	0.09	-	0.20		0.004	-	0.008
C <sub>1</sub>	0.09	-	0.16		0.004	-	0.006
D	9.00 BSC				0.354 BSC		
$D_1$	7.00 BSC				0.276 BSC		
E	9.00 BSC				0.354 BSC		
E <sub>1</sub>	7.00 BSC				0.276 BSC		
е	0.50 BSC				0.020 BSC		
L	0.45	0.60	0.75		0.018	0.024	0.030
$L_1$	1.00 REF				0.039 REF		
R <sub>1</sub>	80.0	ı	-		0.003	-	-
$R_2$	80.0	-	0.20		0.003	-	0.008
S	0.20	ı			0.008	-	ı
θ	0°	3.5°	7°		0°	3.5°	7°
θ <sub>1</sub>	0°	-	-		0°	=	-
$\theta_2$	12° TYP				12° TYP		
$\theta_3$	12° TYP				12° TYP		

- 1. Dimension  $D_1$  and  $E_1$  do not include resin fin.
- 2. All dimensions are base on metric system.
- 3. General appearance spec should base on its final visual inspection spec.

Final



#### 11. Order Information

Part Number	Pin Count	Package
DM9161AE	48	LQFP
DM9161AEP	48	LQFP(Pb-Free)

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Conditions beyond those listed for the absolute maximum may destroy or damage the products. In addition, conditions for sustained periods at near the limits of the operating ranges will stress and may temporarily (and permanently) affect and damage structure, performance and/or function.

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